



ESSENSE

Esca Surveillance and Sensing in Serbian Vineyards



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Sub-project team

Veles Sense

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Goals & Objectives

Evaluate the BC8 bundle

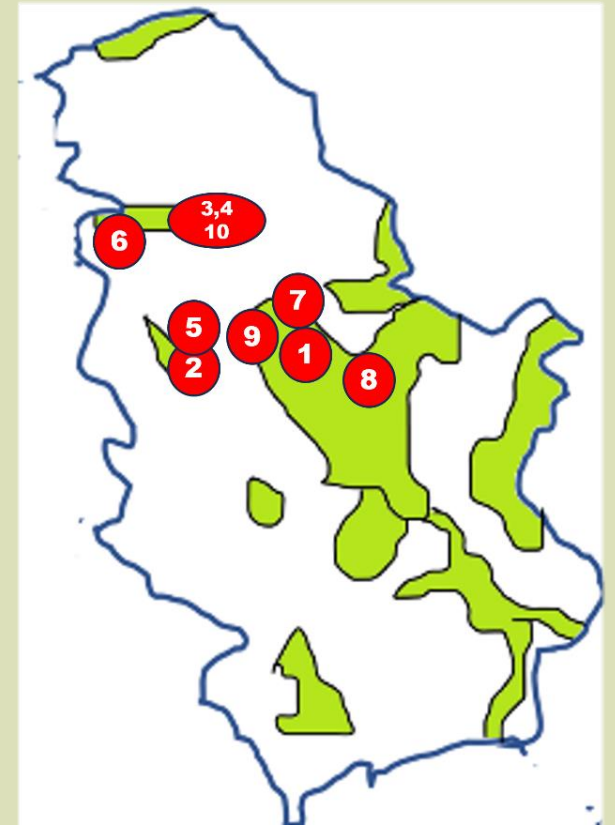
01 Objectives of the ESSENSE project

Objective 1: Select some of Serbia's most renowned and diverse wine regions

Objective 2: Utilize collected data from the 2023 and 2024 seasons for testing the BC8 bundle

Objective 3: Upload the selected data to the CHAMELEON tool for comprehensive analysis

Objective 4: Validate the results through several distinct validation approaches





Data processing

Data acquisition in Serbian vineyards

02 Data acquisition

Pre-seasonal and seasonal data

Data from at least two periods should be used

- **Pre-seasonal data** (February 2025) to facilitate automatic vine detection
- **Seasonal data** (May-August 2024) to facilitate crop growth monitoring process

Equipment: DJI Mavic 3 Multispectral: RGB + multispectral imaging

- ✓ Green (550 +- 16 nm), Red (650 +- 16 nm), RedEdge (730 +- 16 nm), Near-Infrared (860 +- 26 nm)
- ✓ Drone flying altitude: 50 to 100 meters
- ✓ Forward patch overlap: 60% and 70%
- ✓ Side patch overlap: 40%, 50%, and 70%
- ✓ Multispectral camera orientation: NADIR

02 Data acquisition

Pre-seasonal and seasonal data



February 2025

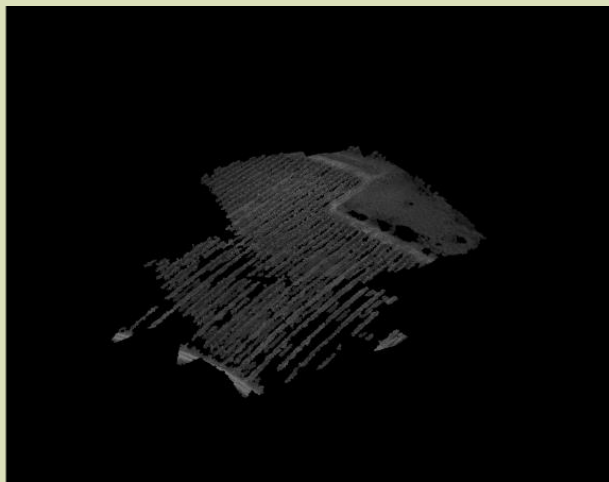
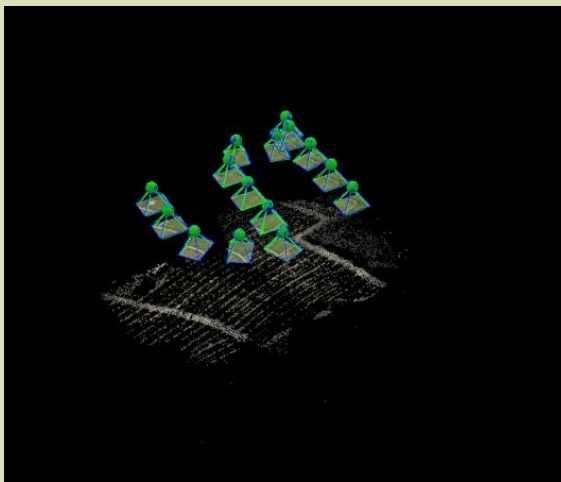


August 2024



02 Data pre-processing

1. Creation of orthophoto and other geospatial products (in Pix4D)
2. Creation of polygon shapefile in GIS software (in QGIS)
3. Extraction of the individual vines



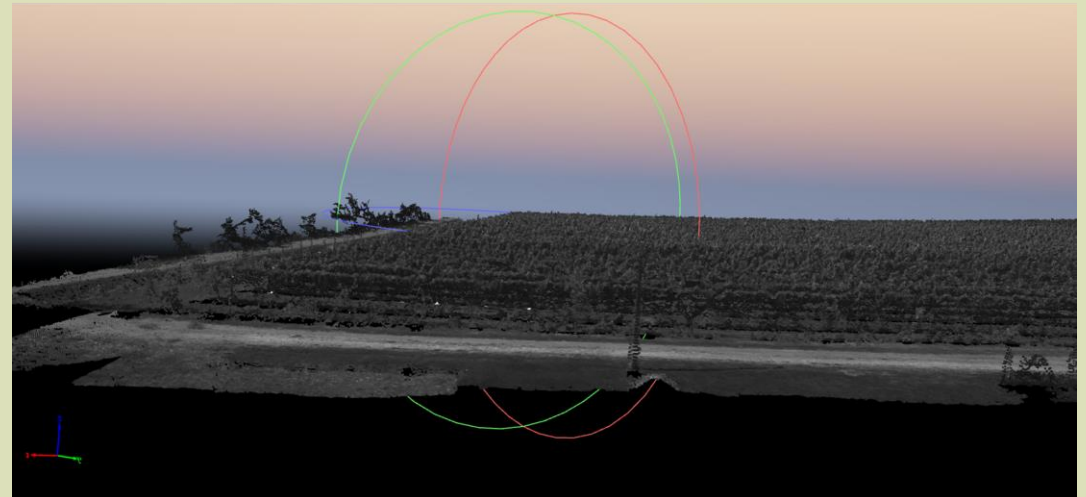
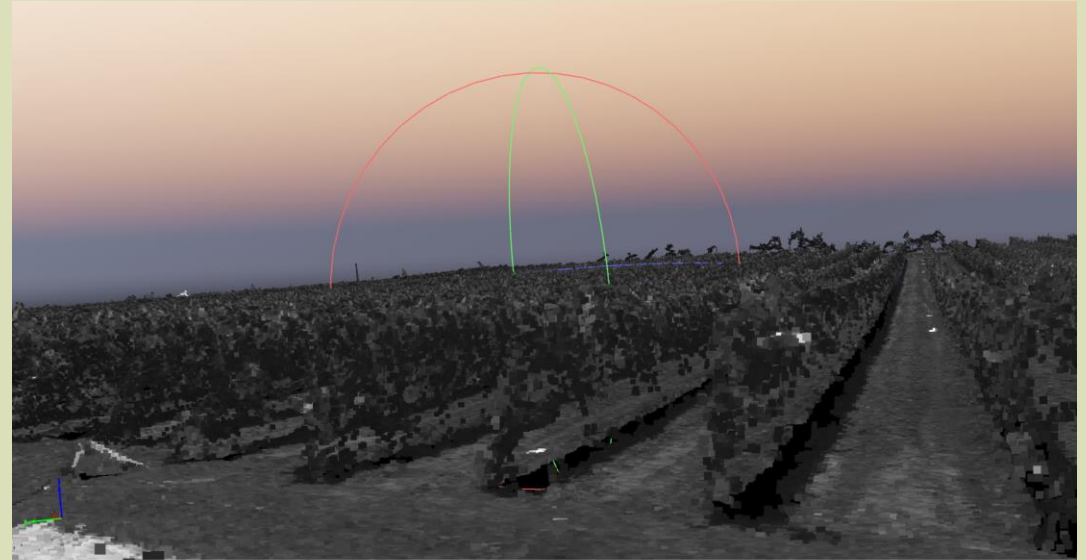
Point clouds



ROI

02 Point clouds

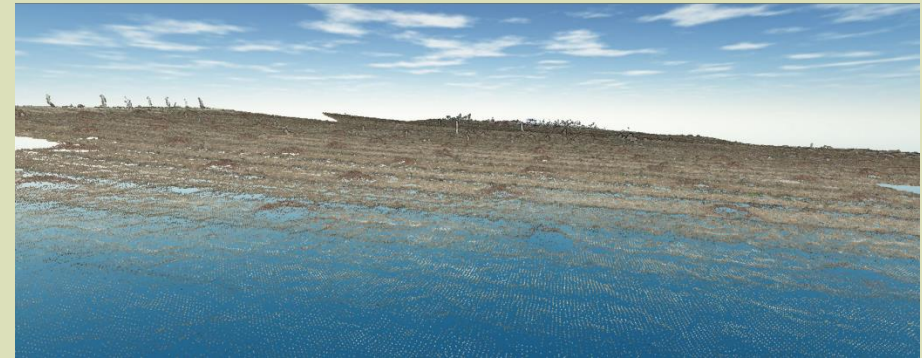
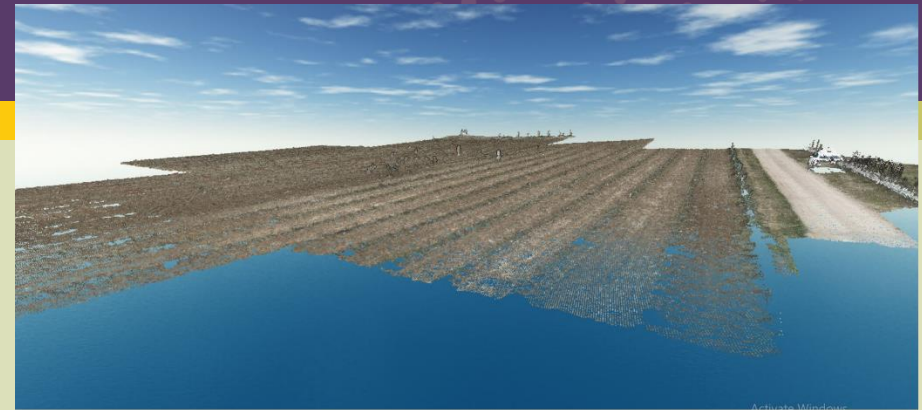
- Generation of point clouds is done in commercial software – Pix4D
- The quality of the point clouds strongly depends on several factors such as
 - o camera resolution (higher better),
 - o drone flying altitude (lower better),
 - o patch overlapping settings (higher better)



02 Automatic vines detection

With PAFyC Tool

- Automatic vines detection can be done by using PAFyC Tool and pre-seasonal data
- PAFyC is not stand-alone (requires installation of additional tools such as QGIS)
- The quality of point clouds from DJI Mavic 3 M is not enough for successful automatic vine detection!





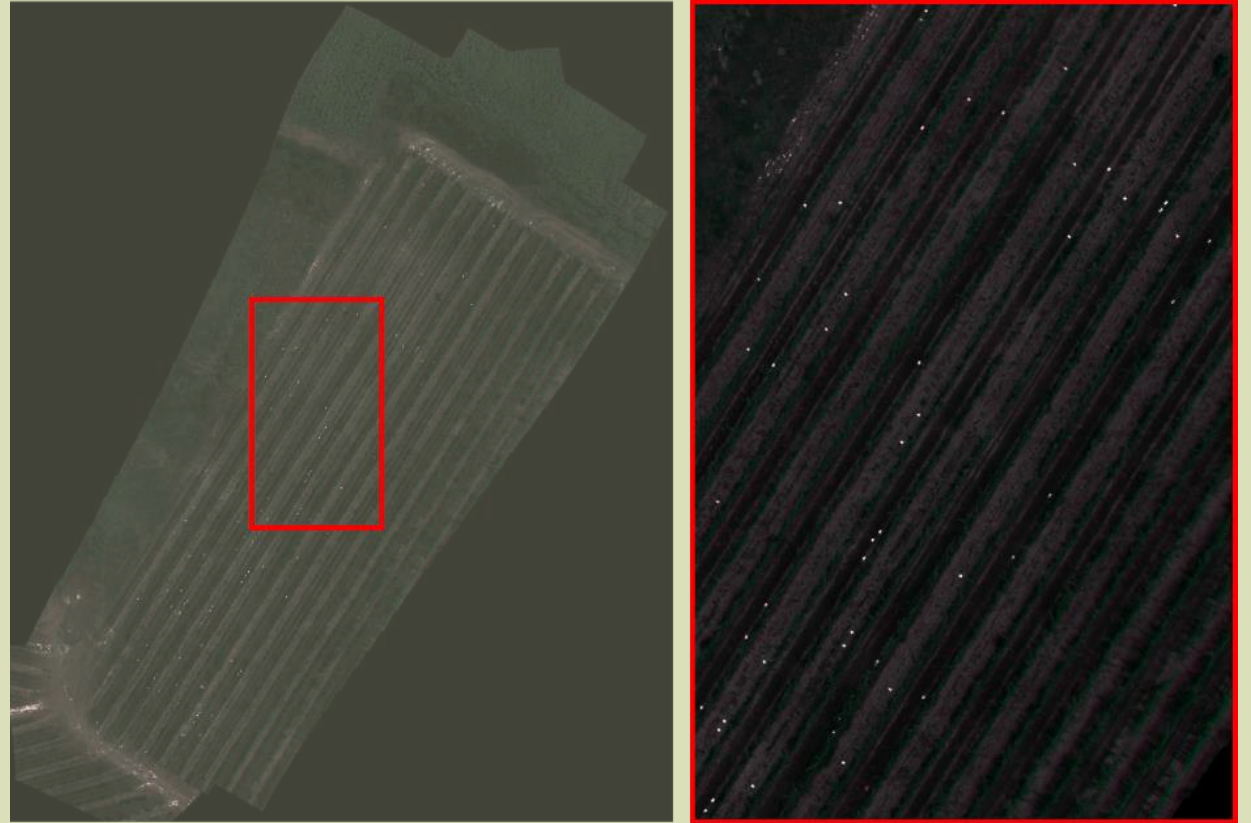
Results evaluation

Ground truth maps and Vegetation Indices

03 Results evaluation

Ground truth maps

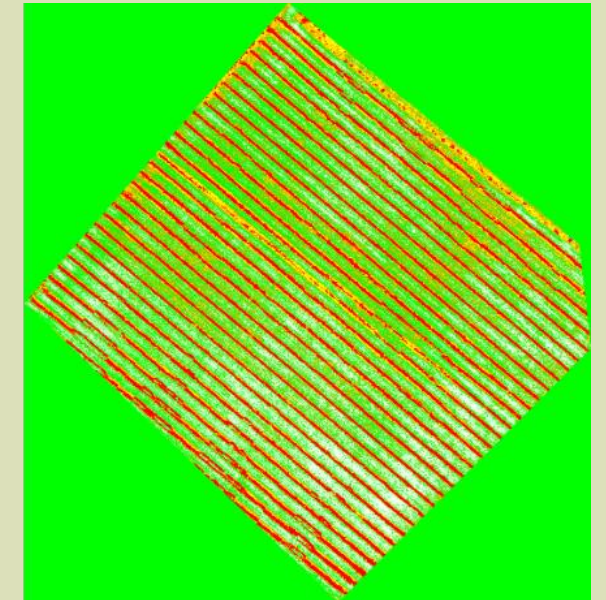
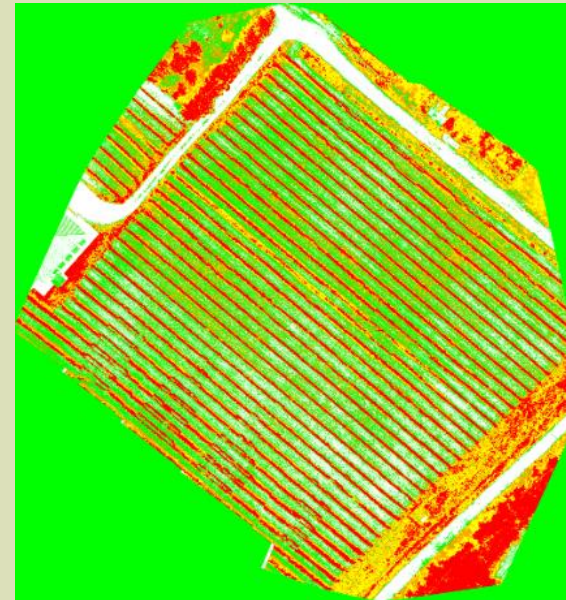
- Developed ground truth maps (and masks) that show the location of vines under stress including
- vines with Esca disease
- suspected Esca
- and other symptoms



03 Results evaluation

Vegetation Indices

- Vegetation Indices are calculated on the whole map and on selected ROIs
- Python script for ROI selection is developed



03 Risks and Mitigation

- PAFyC tool has hardcoded EPSG codes of the coordinate system

CRS 25830 was chosen by default. In Serbia, CRS 32634 is used which was not provided in the tool available for selection.

- For the proper usage of the tool, the user needs to have additional software installed and access to a commercial software for creation of orthomosaics.
- The point clouds generated from DJI Mavic 3 Multispectral should be of appropriate quality for successful testing of the BC8 bundle.



Communication and dissemination

04 Communication

LinkedIn posts



Traditional media



04 Communication

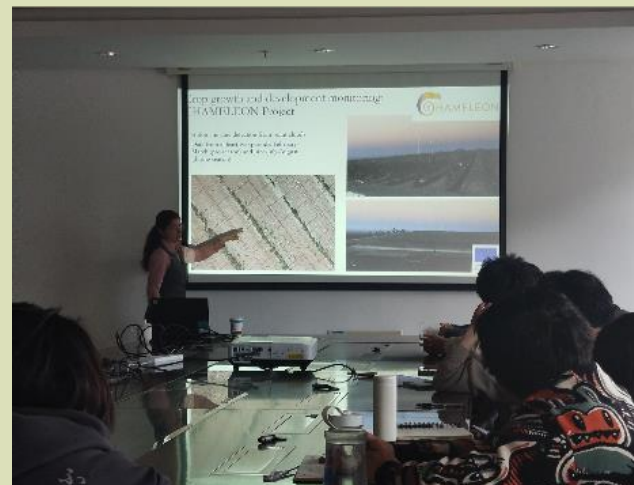
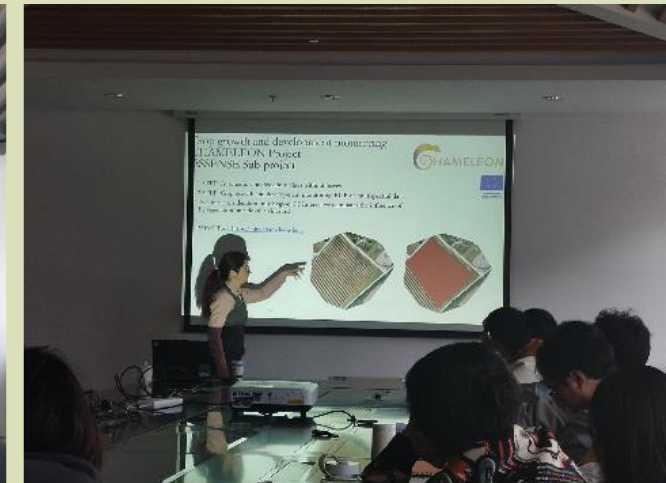
Stakeholder engagement

- ✓ major industry events,
- ✓ trade fairs,
- ✓ symposia, and
- ✓ targeted site visits



04 Dissemination

- ✓ Conference presentation (abstract accepted!)
- ✓ Invited lecture at Aerospace Information Research Institute, Chinese Academy of Sciences, Beijing, China
- ✓ Journal draft to be submitted to open-access journal



Team



Žarko Ljubenović

CEO

Sales & Marketing; Drone pilot

Experience in retail and
wholesale

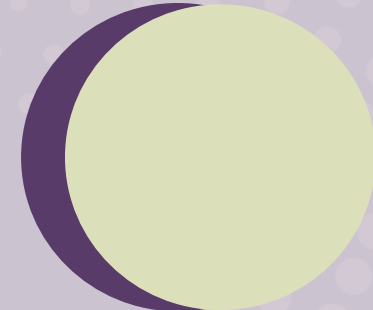


Marina Ljubenović

CTO

Research & Development

18+ years in digital image
processing



External collaborators

Zoran Bešlić

full professor of viticulture

Miroslav Dobrosavljević,
remote-sensing expert



*Thank you for your attention!
Do you have any questions?*



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